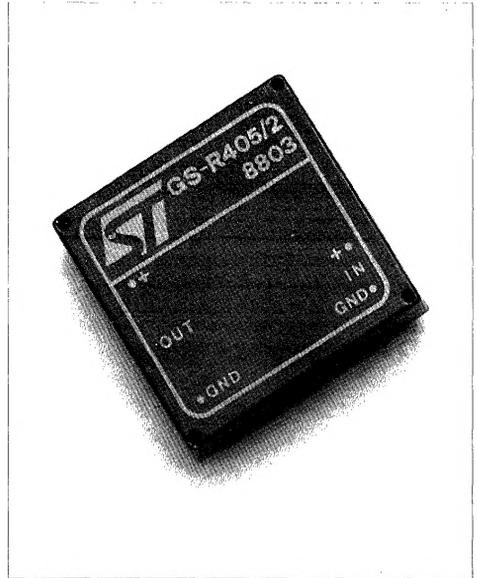


## SWITCHING VOLTAGE REGULATOR MODULES

- MTBF IN EXCESS OF 500.000 HOURS
- NO EXTERNAL COMPONENTS REQUIRED
- PC CARD OR CHASSIS MOUNTABLE
- HIGH OUTPUT CURRENT (4 A)
- HIGH INPUT VOLTAGE (40 V)
- FIXED OUTPUT VOLTAGE (5.1 V; 12 V)
- HIGH EFFICIENCY (up to 85 %)
- SOFT START
- NON-LATCHING SHORT CIRCUIT PROTECTION
- THERMAL PROTECTION
- CROW BAR PROTECTION FOR THE LOAD
- HIGH POWER/VOLUME RATIO (24 Watt/cubic inch)



### DESCRIPTION

The GS-R400/2 is a family of SMALL SIZE HIGH CURRENT HIGH VOLTAGE SWITCHING VOLTAGE REGULATORS.

These step down regulators, shielded for EMI, can provide local on-card regulation, or be used in central power supply systems, in both professional and industrial applications.

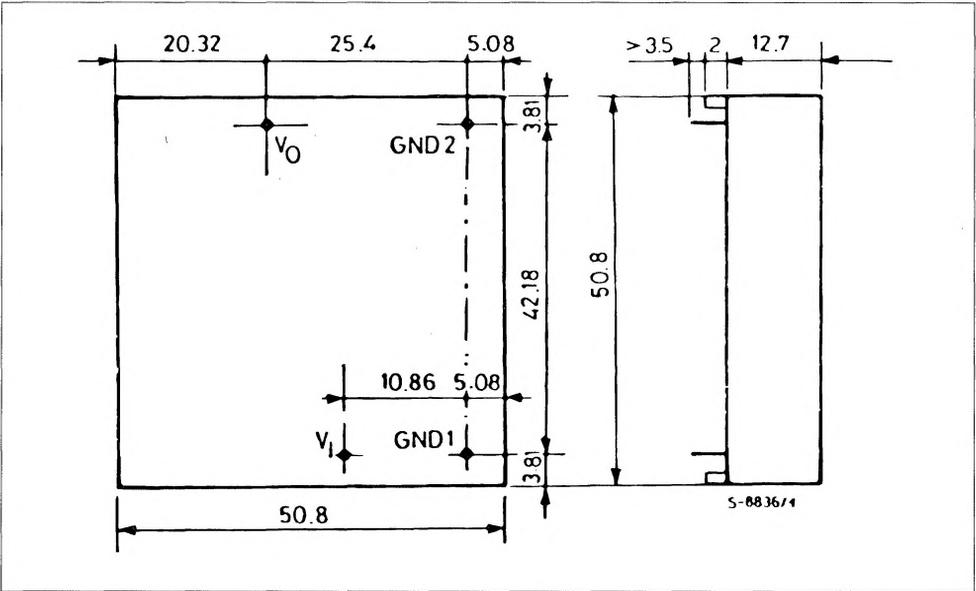
### PRODUCTS FAMILY

| Order Number | Output Voltage |
|--------------|----------------|
| GS-R405/2    | 5.1 V          |
| GS-R412/2    | 12 V           |

### ABSOLUTE MAXIMUM RATINGS

|           |                                  |                 |
|-----------|----------------------------------|-----------------|
| $V_i$     | DC input voltage                 | 40 V            |
| $I_o$     | Output Current                   | 4 A             |
| $T_{stg}$ | Storage temperature range        | - 40 to + 105°C |
| $T_{cop}$ | Operating case temperature range | - 20 to + 85°C  |

## MECHANICAL DIMENSIONS AND CONNECTION DIAGRAM (Bottom view)



## PIN FUNCTIONS

|         | PIN              | FUNCTION  |
|---------|------------------|---|
| $V_i$   | - Input Voltage  | Unregulated DC voltage input. Maximum voltage must not exceed 40 V.   |
| $GND_1$ | - Ground         | Common ground for input voltage.  |
| $GND_2$ | - Ground         | Common ground of high current path.   |
| $V_o$   | - Output Voltage | Regulated and stabilized DC voltage is available on this pin. Max output current is 4 A.<br>The device is protected against short circuit of this pin to ground or to supply. |

The case is electrically connected to GND.

ELECTRICAL CHARACTERISTICS ( $T_{amb} = 25^{\circ}\text{C}$  Unless otherwise specified)

| TYPE         |                              |   | GS-R 405/2 |      |      | GS-R 412/2 |      |      | UNIT     |
|--------------|------------------------------|---|------------|------|------|------------|------|------|----------|
| PARAMETER    | Test Condit.                 |   | Min.       | Typ. | Max. | Min.       | Typ. | Max. |          |
| $V_o$        | Output Voltage               | $V_i = 24\text{ V } I_o = 1\text{ A}$                     | 5          | 5.1  | 5.2  | 11.5       | 12   | 12.5 | V        |
| $V_o$        | Temperature Stability        | $V_i = 24\text{ V } I_o = 1\text{ A}$                     | 0.2        |      |      | 0.5        |      |      | mv<br>°C |
| $V_i$        | Input Voltage                | $I_o = 1\text{ A}$  | 9          | 40   |      | 16         | 40   |      | V        |
| $I_o$        | Output Current*              | $V_i = 24\text{ V}$                                       | 0.1        | 4    |      | 0.1        | 4    |      | A        |
| $I_{OL}$     | Current Limit                | $V_i = V_o + 8\text{ V}$                                  | 5          |      | 8    | 5          |      | 8    | A        |
| $I_{sc}$     | Average Input Current        | $V_i = 40\text{ V}$<br>Output shorted                     | 0.1        |      | 0.2  | 0.1        |      | 0.2  | A        |
| $f_s$        | Switching Frequency          |   | 100        |      |      | 100        |      |      | kHz      |
| $\eta$       | Efficiency                   | $V_i = 24\text{ V}$<br>$I_o = 2\text{ A}$                 | 80         |      |      | 85         |      |      | %        |
| $\Delta V_o$ | Line Regulation              | $I_o = 1\text{ A}$<br>$V_i = 16\text{ to }26\text{ V}$    | 2          |      |      | 2          |      |      | mV/V     |
| SVR          | Supply Voltage rejection     | $f = 100\text{ Hz}$<br>$I_o = 1\text{ A}$                 | 4          |      |      | 6          |      |      | mV/V     |
| $\Delta V_o$ | Load Regulation              | $V_i = 24\text{ V}$<br>$I_o = 0.5\text{ to }1.5\text{ A}$ | 20         |      |      | 40         |      |      | mV/A     |
| $V_r$        | Ripple Voltage               | $I_{out} = 2\text{ A}$                                    | 25         |      |      | 50         |      |      | mV       |
| $V_n$        | Noise Voltage                | $I_{out} = 2\text{ A}$                                    | 25         |      |      | 35         |      |      | mV       |
| $I_r$        | Reflected $I_{in}$           | $V_i = 24\text{ V}$<br>$I_o = 1\text{ A}$                 | 60         |      |      | 120        |      |      | mA       |
| $T_{r1}$     | Line Transient recovery time | $I_o = 1\text{ A}$<br>$V_i = 16\text{ to }26\text{ V}$    | 500        |      |      | 500        |      |      | ms       |
| $T_{r2}$     | Load Transient recovery time | $V_i = 24\text{ V}$<br>$V_i = 0.5\text{ to }1.5$          | 100        |      |      | 100        |      |      | ms       |
| $R_{th}$     | Thermal resistance           |   | 8          |      |      | 8          |      |      | °C/W     |
| $t_{ss}$     | Soft start time              | $V_{in} = V_{out} + 10\text{ V}$                          | 15         |      |      | 25         |      |      | ms       |
| $t_{CB}$     | Crow bar Delay Time          |   | 5          |      |      | 5          |      |      | ms       |
| $V_{CB}$     | Crow bar Delay Threshold     |   | 6          |      |      | 14.5       |      |      | V        |

\* The maximum current can be delivered when  $t_{case} < 85^{\circ}\text{C}$ . Forced ventilation or additional heat-sink may be required to keep  $T_{case} < 85^{\circ}\text{C}$ .

### MODULE OPERATION

The GSR400/2 series is a family of step down switching mode voltage regulators.

Unregulated DC input voltage must be higher than nominal output voltage by, at least, 4 V.

Minimum input voltage is therefore 9 V for GS-R405/2 and maximum input voltage is 40 V for all the types.

The output voltage is fixed and the maximum current delivered by the output pin is 4A. A minimum output current of 100 mA is required for proper

module operation. In no-load condition, the module still works, but the electrical characteristics are slightly modified vs. specifications.

To prevent excessive over current at switch on, a soft start function is provided. Nominal output voltage is approached gradually in about 15 to 25 ms.

The switching frequency of the module is 100 KHz. To prevent EMI, the module is contained in a metal box that provides shielding and heat-sink.

### MODULE PROTECTIONS

#### Thermal Protection

The module is provided with a thermal protection. When ambient temperature reaches prohibitive values, so that internal junction temperature of active components reaches 150 °C, the module is switched off. Normal operation is restored when internal junction temperature falls below 130°C : this large hysteresis allows an extremely low frequency intermittent operation (ON - OFF) caused by thermal overload.

#### Short Circuit Protection

The module is protected against occasional and permanent short circuits of the output pin to ground or against output current overloads.

When the output current exceeds the maximum allowed value for safe operation, the output is automatically disabled. After a fixed time, the module starts again in a soft mode : if the overload is

still present, the module switches off and the cycle is repeated until the overload condition is removed. The average overload current is limited to a safe value for the module itself. Input current during output short circuit is always lower than in regular operation.

#### Load Protection

The module protects, by a crow bar circuit, the load connected to its output against overvoltages. This circuit senses continuously the output voltage : if, for any reason, the output voltage of the module exceeds by + 20 % the nominal value, the crow bar protection is activated and it short circuits the output pin to ground. This protection prevents also damages to the module if the output pin is wrongly connected to the supply voltage.

## OPERATING AMBIENT TEMPERATURE RANGE

The GS-R400/2 modules are power devices, i.e. devices that deliver and dissipate power. The power dissipation is related to the delivered output power by

$$P_d = P_o \left( \frac{1}{\eta} - 1 \right)$$

where  $\eta = \text{efficiency} = \frac{P_o}{P_{IN}}$

The operating ambient temperature range cannot be simply defined by numbers because it depends on many conditions that must be previously defined.

On the contrary, the operating case temperature is well defined and it ranges from - 20 to + 85 °C.

The two extremes are imposed by reliable operation of aluminium electrolytic capacitors that are housed inside the modules.

From these data, the maximum ambient temperature range can be easily calculated, as shown in the following example :

$$V_{IN} = 24V \quad V_{OUT} = 5V ; 12V \quad I_{OUT} = 3A.$$

The dissipated powers of GS-R405/2 and GS-R412/2 are respectively :

$$P_{d\ 5V} = 3.75W \quad P_{d\ 12V} = 6.4W$$

By knowing the thermal resistance case to ambient  $R_{TH} = 8^\circ\text{C} / \text{W}$  for natural convection condition, the maximum ambient temperature for a case maximum temperature of 85°C will be

$$T_{amb\ max} = T_{case\ max} - P_d \cdot R_{TH}$$

i.e.

$$T_{amb\ 5V} = 85 - 3.75 \cdot 8 = 55^\circ\text{C max}$$

$$T_{amb\ 12V} = 85 - 8 \cdot 6.4 = 34^\circ\text{C max}$$

This ambient temperature can be increased by lowering the thermal resistance case to ambient. Various methods can be adopted such as addition of external heat-sink on forced ventilation or both.

If an external heat-sink with  $R_{TH} = 10^\circ\text{C}/\text{W}$  is used, the values are modified as follows.

The total thermal resistance case to ambient is the parallel of the two thermal resistances

$$R_{TH\ TOT} = \frac{R_{TH\ CASE} \cdot R_{TH\ HEAT-SINK}}{R_{TH\ CASE} + R_{TH\ HEAT-SINK}} = 4,5^\circ\text{C}/\text{W}$$

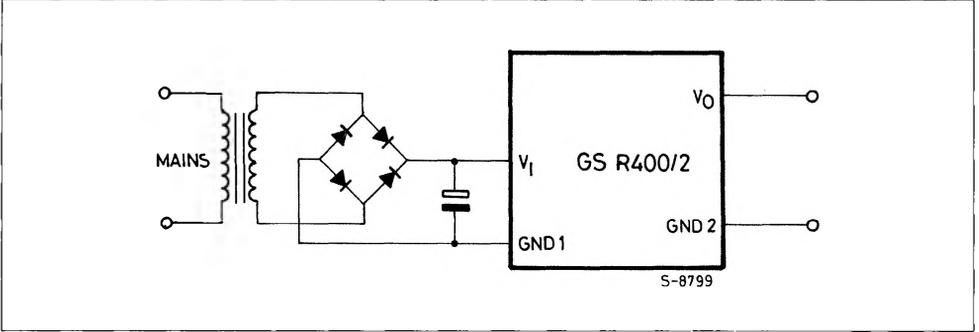
$$T_{amb\ 5V} = 68^\circ\text{C max} \quad T_{amb\ 12V} = 56^\circ\text{C max}$$

**TYPICAL APPLICATIONS**

The high input voltage range allows both cost saving on 50/60 Hz transformer when the module is supplied from the mains, and the possibility to

supply the module with batteries that, according to their charge status, can show large spread on voltage.

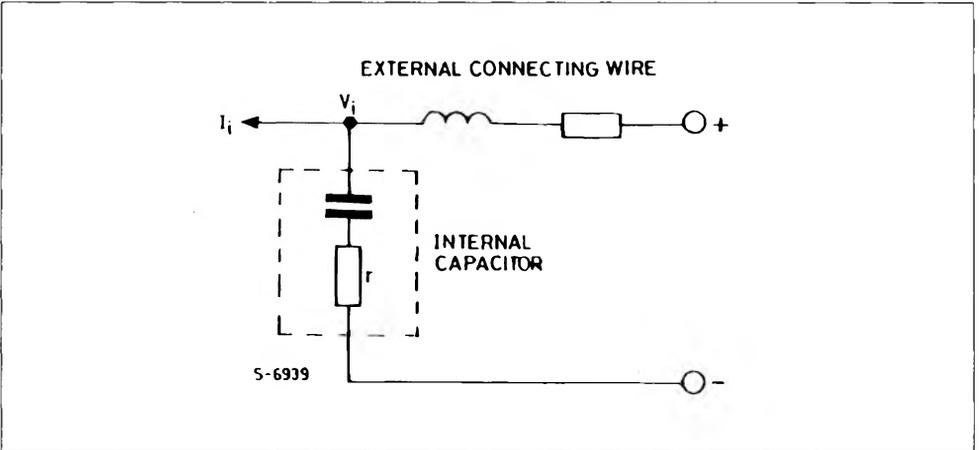
**Figure 1 - A Typical Application of GS-R400/2 Voltage Regulator**



The module has, internally, an input filtering capacitor between pin  $V_1$  and  $GND_1$ . Therefore, at

the switching frequency the equivalent input circuit is as shown in fig. 2.

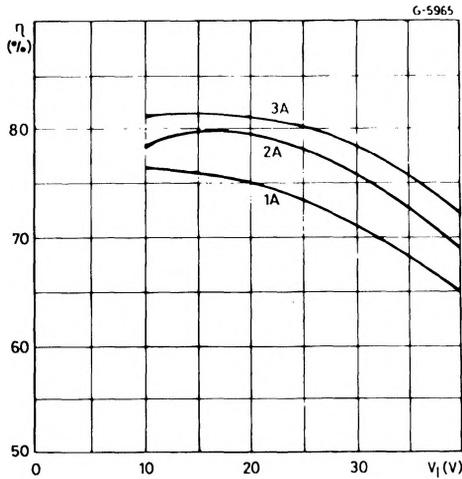
**Figure 2 - Equivalent Input Circuit of GS-R400/2 Voltage Regulator**



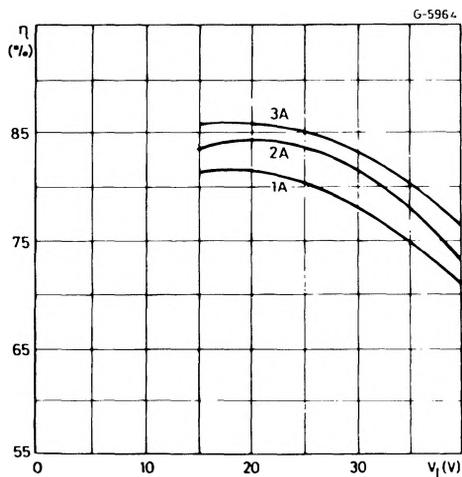
Since  $I_1$  is a high frequency alternating current, the inductance associated to long input connecting wire can cause a voltage ripple on point  $V_1$  that produces a ripple current across internal capacitor and a power dissipation on r.

When very long connecting wires are used, the input capacitor may be damaged by this power dissipation. For this reason it is suggested to keep input connecting wires as short as possible.

**EFFECIENCY VS. INPUT VOLTAGE & OUTPUT CURRENT**



GS-R405/2



GS-R412/2