



8214

PRIORITY INTERRUPT CONTROL UNIT

- Eight Priority Levels
- Current Status Register
- Priority Comparator
- Fully Expandable
- High Performance (50ns)
- 24-Pin Dual In-Line Package

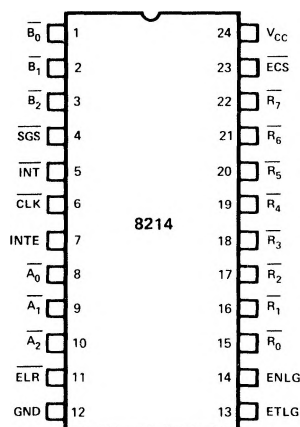
The 8214 is an eight level priority interrupt control unit designed to simplify interrupt driven microcomputer systems.

The PICU can accept eight requesting levels; determine the highest priority, compare this priority to a software controlled current status register and issue an interrupt to the system along with vector information to identify the service routine.

The 8214 is fully expandable by the use of open collector interrupt output and vector information. Control signals are also provided to simplify this function.

The PICU is designed to support a wide variety of vectored interrupt structures and reduce package count in interrupt driven microcomputer systems.

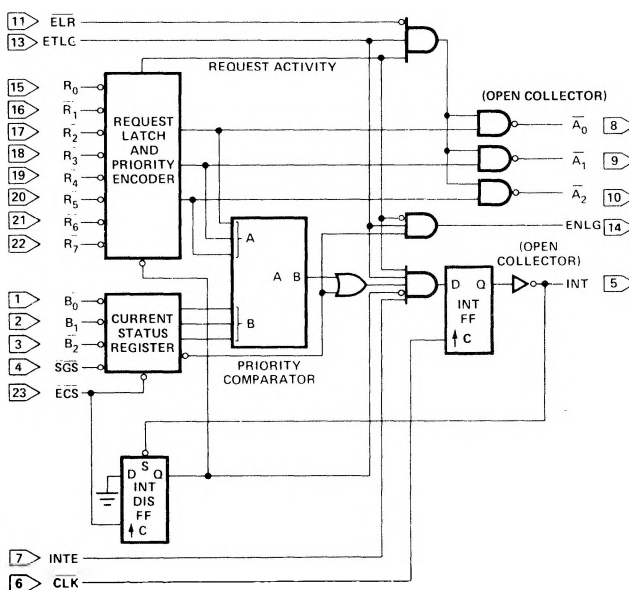
PIN CONFIGURATION



PIN NAMES

INPUTS		
R ₀ -R ₇	REQUEST LEVELS (R ₇ HIGHEST PRIORITY)	
B ₀ -B ₂	CURRENT STATUS	
SGS	STATUS GROUP SELECT	
ECS	ENABLE CURRENT STATUS	
INTE	INTERRUPT ENABLE	
CLK	CLOCK (INT F-F)	
ELR	ENABLE LEVEL READ	
ETLG	ENABLE THIS LEVEL GROUP	
OUTPUTS		
A ₀ -A ₂	REQUEST LEVELS	] OPEN COLLECTOR
INT	INTERRUPT (ACT. LOW)	
ENLG	ENABLE NEXT LEVEL GROUP	

LOGIC DIAGRAM



D.C. AND OPERATING CHARACTERISTICS

ABSOLUTE MAXIMUM RATINGS*

Temperature Under Bias 0°C to 70°C
 Storage Temperature -65°C to +150°C
 All Output and Supply Voltages -0.5V to +7V
 All Input Voltages -1.0V to +5.5V
 Output Currents 100 mA

**COMMENT: Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.*

$T_A = 0^\circ\text{C}$ to $+70^\circ\text{C}$, $V_{CC} = 5\text{V} \pm 5\%$.

Symbol	Parameter	Limits			Unit	Conditions
		Min.	Typ.[1]	Max.		
V_C	Input Clamp Voltage (all inputs)			-1.0	V	$I_C = -5\text{mA}$
I_F	Input Forward Current: ETLG input all other inputs		-.15 -.08	-0.5	mA	$V_F = 0.45\text{V}$
				-0.25	mA	
I_R	Input Reverse Current: ETLG input all other inputs			80	μA	$V_R = 5.25\text{V}$
				40	μA	
V_{IL}	Input LOW Voltage: all inputs			0.8	V	$V_{CC} = 5.0\text{V}$
V_{IH}	Input HIGH Voltage: all inputs	2.0			V	$V_{CC} = 5.0\text{V}$
I_{CC}	Power Supply Current		90	130	mA	See Note 2.
V_{OL}	Output LOW Voltage: all outputs		.3	.45	V	$I_{OL} = 15\text{mA}$
V_{OH}	Output HIGH Voltage: ENLG output	2.4	3.0		V	$I_{OH} = -1\text{mA}$
I_{OS}	Short Circuit Output Current: ENLG output	-20	-35	-55	mA	$V_{OS} = 0\text{V}$, $V_{CC} = 5.0\text{V}$
I_{CEX}	Output Leakage Current: INT and $\overline{A_0}$ - $\overline{A_2}$			100	μA	$V_{CEX} = 5.25\text{V}$

NOTES:

- Typical values are for $T_A = 25^\circ\text{C}$, $V_{CC} = 5.0\text{V}$.
- B_0 - B_2 , $\overline{SGS}$, CLK, $\overline{R_0}$ - $\overline{R_4}$ grounded, all other inputs and all outputs open.

A.C. CHARACTERISTICS AND WAVEFORMS $T_A = 0^\circ\text{C to } +70^\circ\text{C}$, $V_{CC} = +5\text{V} \pm 5\%$

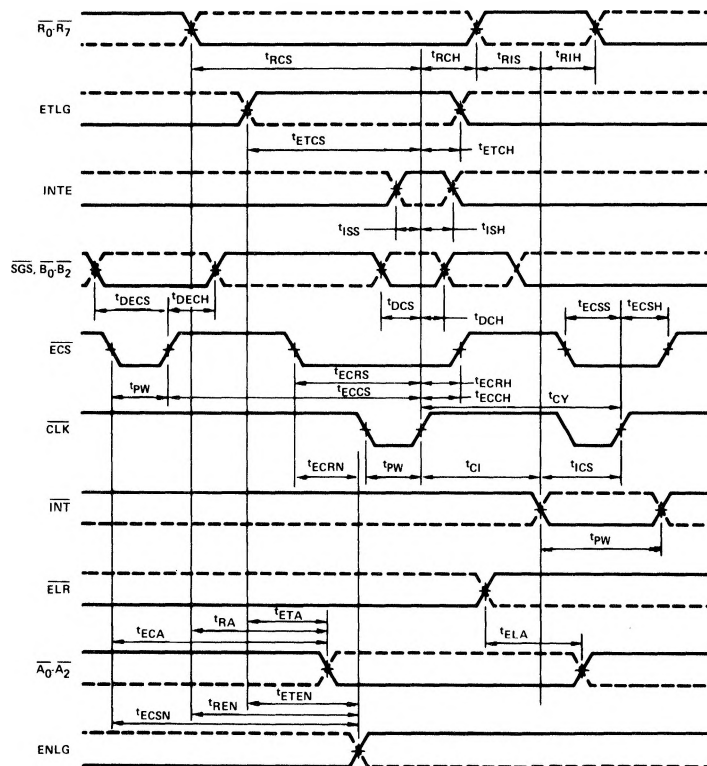
Symbol	Parameter	Limits			Unit
		Min.	Typ. ^[1]	Max.	
t_{CY}	CLK Cycle Time	80	50		ns
t_{PW}	CLK, ECS, INT Pulse Width	25	15		ns
t_{ISS}	INTE Setup Time to CLK	16	12		ns
t_{ISH}	INTE Hold Time after CLK	20	10		ns
$t_{ETCS}^{[2]}$	ETLG Setup Time to CLK	25	12		ns
$t_{ETCH}^{[2]}$	ETLG Hold Time After CLK	20	10		ns
$t_{ECCS}^{[2]}$	ECS Setup Time to CLK	80	50		ns
$t_{ECCH}^{[3]}$	ECS Hold Time After CLK	0			ns
$t_{ECRS}^{[3]}$	ECS Setup Time to CLK	110	70		ns
$t_{ECRH}^{[3]}$	ECS Hold Time After CLK	0			
$t_{ECSS}^{[2]}$	ECS Setup Time to CLK	75	70		ns
$t_{ECSH}^{[2]}$	ECS Hold Time After CLK	0			ns
$t_{DCS}^{[2]}$	SGS and $\overline{B_0-B_2}$ Setup Time to CLK	70	50		ns
$t_{DCH}^{[2]}$	SGS and $\overline{B_0-B_2}$ Hold Time After CLK	0			ns
$t_{RCS}^{[3]}$	$\overline{R_0-R_7}$ Setup Time to CLK	90	55		ns
$t_{RCH}^{[3]}$	$\overline{R_0-R_7}$ Hold Time After CLK	0			ns
t_{ICS}	INT Setup Time to CLK	55	35		ns
t_{CI}	CLK to INT Propagation Delay		15	25	ns
$t_{RIS}^{[4]}$	$\overline{R_0-R_7}$ Setup Time to INT	10	0		ns
$t_{RIH}^{[4]}$	$\overline{R_0-R_7}$ Hold Time After INT	35	20		ns
t_{RA}	$\overline{R_0-R_7}$ to $\overline{A_0-A_2}$ Propagation Delay		80	100	ns
t_{ELA}	$\overline{ELR}$ to $\overline{A_0-A_2}$ Propagation Delay		40	55	ns
t_{ECA}	ECS to $\overline{A_0-A_2}$ Propagation Delay		100	120	ns
t_{ETA}	ETLG to $\overline{A_0-A_2}$ Propagation Delay		35	70	ns
$t_{DECS}^{[4]}$	SGS and $\overline{B_0-B_2}$ Setup Time to ECS	15	10		ns
$t_{DECH}^{[4]}$	SGS and $\overline{B_0-B_2}$ Hold Time After ECS	15	10		ns
t_{REN}	$\overline{R_0-R_7}$ to ENLG Propagation Delay		45	70	ns
t_{TEN}	ETLG to ENLG Propagation Delay		20	25	ns
t_{ECRN}	ECS to ENLG Propagation Delay		85	90	ns
t_{ECSN}	ECS to ENLG Propagation Delay		35	55	ns

CAPACITANCE^[5]

Symbol	Parameter	Limits			Unit
		Min.	Typ. ^[1]	Max.	
C_{IN}	Input Capacitance		5	10	pF
C_{OUT}	Output Capacitance		7	12	pF

TEST CONDITIONS: $V_{BIAS} = 2.5\text{V}$, $V_{CC} = 5\text{V}$, $T_A = 25^\circ\text{C}$, $f = 1\text{ MHz}$
NOTE 5. This parameter is periodically sampled and not 100% tested.

WAVEFORMS



NOTES:

- (1) Typical values are for $T_A = 25^\circ\text{C}$, $V_{CC} = 5.0\text{V}$.
- (2) Required for proper operation if ISE is enabled during next clock pulse.
- (3) These times are not required for proper operation but for desired change in interrupt flip-flop.
- (4) Required for new request or status to be properly loaded.

TEST CONDITIONS:

Input pulse amplitude: 2.5 volts.

Input rise and fall times: 5 ns between 1 and 2 volts.

Output loading of 15 mA and 30 pf.

Speed measurements taken at the 1.5V levels.

TEST LOAD CIRCUIT

